Mapping habitat indices across river networks using spatial statistical modelling of River Habitat Survey data.

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17 Abstract

Freshwater ecosystems are declining faster than their terrestrial and marine counterparts because of physical pressures on habitats. European legislation requires member states to achieve ecological targets through the effective management of freshwater habitats. Maps of habitats across river networks would help diagnose environmental problems and plan for the delivery of improvement work. Existing habitat mapping methods are generally time consuming, require experts and are expensive to implement. Surveys based on sampling are cheaper but provide patchy

representations of habitat distribution. In this study, we present a method for mapping 25 habitat indices across networks using semi-quantitative data and a geostatistical 26 technique called regression kriging. The method consists of the derivation of habitat 27 28 indices using multivariate statistical techniques that are regressed on map-based covariates such as altitude, slope and geology. Regression kriging combines the 29 Generalised Least Squares (GLS) regression technique with a spatial analysis of 30 model residuals. Predictions from the GLS model are 'corrected' using weighted 31 averages of model residuals following an analysis of spatial correlation. The method 32 33 was applied to channel substrate data from the River Habitat Survey in Great Britain. A Channel Substrate Index (CSI) was derived using Correspondence Analysis and 34 predicted using regression kriging. The model explained 74% of the main sample 35 36 variability and 64% in a test sample. The model was applied to the English and Welsh river network and a map of CSI was produced. The proposed approach demonstrates 37 how existing national monitoring data and geostatistical techniques can be used to 38 produce continuous maps of habitat indices at the national scale. 39

Keywords: habitat mapping, habitat indices, channel substrate, regression kriging, River
 Habitat Survey, geostatistics

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43 **1. Introduction**

Freshwater ecosystems represent less than 1% of the Earth's surface and 10% of all
known species, yet they are declining faster and are more endangered than their
terrestrial or marine counterparts, partly because of physical pressures on habitats and
species (Loh et al., 2005; Revenga et al., 2005; Strayer and Dudgeon, 2010; Vorosmarty
et al., 2010; WWF, 2014).

Although research in ecology and environmental management has grown substantially in the past half-century, it has mainly focused on post-industrial issues such as water quality, pollution and land use impacts (Vaughan et al., 2009). With gradual improvement in water quality, other limiting factors such as physical habitat quality (i.e. the naturalness of the flow of water, and the structure and composition of the river bed and banks) and connectivity have become prominent.

Globally, degradation of physical habitat quality due to river engineering and associated 55 activities (e.g. constructions of dams, bridges, concrete banks, dredging) is recognised as 56 57 a major conservation issue (Collen et al., 2014; Sala et al., 2000; Tockner and Stanford, 2002; World Conservation Monitoring Centre, 1998). In Europe, as part of the 58 implementation of the Water Framework Directive (WFD), member states must assess 59 the ecological condition of rivers and lakes based on the naturalness of a series of 60 biological elements (European Union, 2000). Following the first round of River Basin 61 Management Planning, 56% of water bodies failed to achieve their ecological targets. 62 Engineered structures and 'altered habitats' were the dominant pressures responsible for 63 the failure, ahead of point and diffuse sources of pollution (European Environment 64 65 Agency, 2012). In England and Scotland, the proportion of water bodies failing to achieve ecological targets because of physical alterations was 49% and 37%, respectively 66 (Environment Agency, 2012). The WFD requires member states to mitigate or remove 67

impacts on habitats and species through the implementation of programmes of measuresincluding river restoration.

The effective management of habitats at global and local scales should ideally be based 70 on some knowledge of their distribution and an assessment of their naturalness and 71 72 accessibility. At present, in Great Britain, habitats are either surveyed using semiquantitative methods at randomly selected sites that do not allow for continuous 73 assessments or using habitat mapping techniques over longer stretches of river 74 (Maddock, 1999). Habitat mapping is geographically limited and generally carried out on 75 an ad hoc basis by experts during 'walkover surveys' where habitat features are recorded 76 on maps using mobile Geographic Information System (GIS) or hand-drawn sketches and 77 some broad typologies (Hendry and Cragg-Hine, 1997; Sear et al., 2009). Although such 78 methods provide valuable information on habitat distributions over relatively small areas, 79 they are likely to be too expensive to implement across entire networks. The reliance on 80 expert judgement for assessing habitat types and boundaries may also generate 81 between-surveyor variability in the outputs produced and, as notions of habitat structure 82 evolve, data collected at one point in time may not be comparable to maps produced 83 years later by different experts (Cherrill and Mcclean, 1999). 84

An alternative approach is to use river typologies based on geomorphological templates to predict the occurrence of broad river types along the river continuum. The history of attempts to classify rivers into different types spans at least 125 years, a period over which perhaps a hundred if not more individual efforts to divide and categorise rivers have been made (reviews of the extent of such efforts are given by Downs, 1995; Montgomery and Buffington, 1997; Mosley, 1987; Naiman et al., 1992; Newson et al., 1998; Thorne, 1997).

Most river classification systems are based on the identification of river types using a few 92 key variables representing drivers of geomorphological change or river processes such as 93 stream power, sediment transport and supply (Montgomery and Buffington, 1997; 94 95 Newson et al., 1998; Rosgen, 1994). Although relationships between expert-driven geomorphic types and GIS attributes such as slope and drainage area can be observed, 96 there is a considerable amount of overlap between types, reflecting the potential influence 97 98 of additional driving elements such as channel, bank and hillslope vegetation, climate, woody debris, and natural variability in channel process expression (Church, 2002; 99 100 Montgomery and Buffington, 1997; Rosgen, 1994). Greater differentiation between river types can be achieved by introducing attributes recorded in the field such as relative 101 roughness (Montgomery and Buffington, 1997), shear stress or channel substrate 102 103 (Rosgen, 1994), but this implies that extensive field work is carried out, thus reducing the feasibility of such an approach at national scales. 104

In this article, we propose an alternative approach for mapping habitat elements across 105 entire river networks that does not require continuous surveys of river catchments, but 106 makes use of existing semi-quantitative survey data, GIS and a geostatistical technique 107 called regression kriging (RK). The principle of the method is to identify and define habitat 108 indices representing major dimensions in habitat distribution using known equations, 109 expert systems or multivariate statistical analysis applied to existing habitat data taken 110 111 from national surveys or monitoring programmes. The habitat indices are then predicted 112 using Generalised Least Squares (GLS) linear regression models using GIS map-derived covariates such as altitude, slope, distance from source, discharge and geology which 113 represent the known drivers of habitat/geomorphological change. The model residuals are 114 then analysed using geostatistical functions to identify any remaining spatial correlation 115 and pattern in their distribution. In the presence of spatial correlation, an interpolation 116

method, called kriging, is applied to account for (and, thus remove) any spatially
correlated residual variance such that the interpolated residual predictions can be added
to the GLS regression predictions. The RK model can then be applied to the entire river
network by deriving the GIS covariates at regular spatial intervals (e.g. 500 m).

This paper reports the development and application of the statistical models to a key and poorly mapped habitat element – channel substrate. Channel substrate is a key component of species habitat (Maddock, 1999; Townsend and Hildrew, 1994), and it is one of three elements defining morphological condition under the WFD (European Union, 2000). Channel substrate is also linked to the wider issues of diffuse pollution and agricultural impacts and it is key to our understanding of river and catchment processes (Collins et al., 2014; Rosgen, 1994).

128 2. Material and methods

129 2.1. Index derivation

River Habitat Survey (RHS) data was used to derive an index representing channel 130 substrate. RHS is a CEN-compliant (CEN, 2004) standard methodology for 131 hydromorphological assessment under the WFD that is used in the UK and across 132 Europe (Raven et al., 1997). It is a methodology for recording habitat features for wildlife 133 that has been implemented at more than 25,000 sites in the UK since 1994. From 1994 134 to 1996 and from 2007 to 2008, surveys were carried out at random sites in every 10 km² 135 in England and Wales, thus, ensuring a wide geographical coverage of the river network. 136 RHS records the presence of natural and management features at 10 equally spaced 137 transects or 'spot-checks' along a 500 m reach (Raven et al., 1997). A visual estimate of 138 the dominant channel surface substrate classified into eight categories according to the 139 Wentworth scale (Wentworth, 1922) is recorded at each spot-check. The substrate types 140

recorded (with acronyms in brackets) are bedrock (BE), boulder (BO), cobble (CO),
gravel-pebble (GP), sand (SA), silt (SI), clay (CL) and peat (PE). When channel substrate
is not visible because of depth, water turbidity or the presence of a culvert, surveyors
record the substrate type as 'Not Visible' (NV).

145 RHS spot-check data on channel substrate was tabulated for all existing sites, each row representing a site and each column a substrate type (including 'Not visible'). The 146 channel substrate spot-check table was analysed using Correspondence Analysis (CA). 147 CA is a multivariate analytical technique similar to Principal Component Analysis that is 148 applicable to contingency tables (i.e. tables of counts). CA performs an analysis of the 149 total table inertia and extracts dimensions (or components) representing linear 150 combinations of input variables based on the amount of total inertia explained. Only sites 151 in Great Britain were used as GIS datasets were not available for Northern Ireland at the 152 time of the analyses. 153

To derive the index, we used a subset of 2680 semi-natural RHS sites (i.e. sites with few 154 or no in-channel bank structures or modifications) to reduce the potential influence of 155 modifications on natural channel substrate diversity (Raven et al., 1997). Missing ('Not 156 Visible') values were added as an additional variable in the analyses to account for 157 differences in survey counts when present. The resulting dimensions were investigated 158 for their ecological and geomorphological significance and for the amount of variability 159 (i.e. inertia) they explained. One dimension was chosen to represent substrate and 160 calculate an index score, called the Channel Substrate Index (CSI) for all sites in the RHS 161 162 database.

163 2.2. Regression kriging

RK was applied following an iterative procedure using both Ordinary Least Square (OLS) 164 and GLS regression techniques (Bivand et al., 2008; Webster and Oliver, 2007). The CSI 165 index was first transformed using a Box-Cox procedure and modelled against a series of 166 GIS attributes: four Principal Component Axes (PCA) combining altitude, slope, distance 167 to source and height of source that were shown by Jeffers (1998) and Vaughan et al. 168 (2013) to be strongly correlated to sediment distribution; land use categories from the 169 Land Cover Map 2000 (Fuller et al., 2002); British Geological Survey solid and drift 170 geology categories taken from the 1/625,000 scale maps; hydrometric areas 171 corresponding to large catchment areas; and solid geology age categorised in 11 groups 172 from the pre-Cambrian to the Neogene. Solid geology age was included as a surrogate 173 for hardness as older rocks tend to be harder and display coarser substrate types than 174 softer and younger sedimentary deposits. 175

Nominal attributes such as solid geology, hydrometric area and land use were
transformed into binary indicator variables. Due to the resulting large number of indicator
variables which would have rendered the predictive models difficult to display and
interpret (e.g. there are more than 100 different solid geology types), indicator variables
were grouped based on their relationships to the CSI. Grouping was done by comparing
coefficient values of indicator variables when individually regressed against CSI or
performing ANOVAs.

Only RHS sites with no missing channel substrate spot-check records were retained for
the analysis as their presence introduces a potential bias in channel substrate
representation and prediction. Model selection was performed using the Minitab 16
(Minitab, 2010) linear regression (OLS) best subset selection procedure using Mallows
Cp (all models) on RHS sites from 1994 to 2005 (9473 sites).

Model residuals were analysed for the presence of spatial correlation using a variogram (Webster and Oliver, 2007), which plots semivariance (a measure of dissimilarity) against lag vector (the distance and direction of separation). Spatially uncorrelated data display no observable change in semivariance with an increase in lag distance and are typically represented by a flat variogram. Spatially correlated data are typically represented by a monotonically increasing semivariance as the lag distance between sites increases.

The empirical variogram is first calculated as the average squared difference between 194 pairs of data points at each of a series of lags. It is fitted with a permissible variogram 195 model (the model must not result in negative prediction variances) to describe the shape 196 of the curve and identify the parameters which are required for RK. Of particular 197 relevance are the nugget and the range parameters (assuming that a bounded model 198 such as the spherical or exponential model is fitted). The nugget variance is equal to the 199 200 variance for sites re-surveyed or re-sampled at the same location and expresses microscale variability and survey error. The range is the distance at which the semivariance 201 reaches a plateau and beyond which data are no longer spatially correlated (Webster and 202 Oliver, 2007). 203

The OLS variogram parameters were used as part of an iterative process to estimate the regression parameters using GLS. GLS is preferred to OLS as the latter assumes independence of observations, an unlikely case given spatial correlation (Bivand et al., 2008). Model residuals were checked for the presence of trends and outliers. The models were validated using a leave-one-out cross-validation technique (Bivand et al., 2008; Vaughan and Ormerod, 2003).

The model was applied to all points using the GSTAT kriging procedure. Kriging linearly averages the residual values of surrounding points with weights estimated using the residual variogram (Webster and Oliver, 2007). To reduce processing time, only points

within a radius roughly equal to the distance at which no observable correlation exists (i.e. 213 the range) were selected for kriging. The kriged residuals were then saved and added to 214 the cross-validated predictions from the previous model. A pseudo-R² value for the final 215 predictions was derived by correlating the predicted and observed values. Residuals were 216 computed and checked for their distribution and for signs of remaining spatial correlation. 217 A check of model stability against time was performed by examining the residual 218 distribution for each year of survey. The model was tested on a sample of 3884 sites 219 collected from 2006-2011. 220

The predictive model and kriging procedure were applied to the entire English and Welsh 1:50,000 river network to produce a national map of sediment distribution. To do so, points were generated every 500 m on the river network using RivEX (Hornby, 2010) and the GIS map-based covariates required for prediction were derived for each point.

225 **3. Results**

3.1. Channel Substrate Index

The first two components of the CA explained 21% and 17% of the total inertia (Table 1). The first component represented a gradient between sites dominated by fine substrate such as silt, clay and sand, and sites dominated by coarse substrate such as bedrock and boulders (Fig. 1). The first component was defined by the relative occurrence of all substrate types with a greater contribution from silt which explained 35% of the component inertia (Table 1). The first component explained 42% of silt distribution inertia, 31% of boulder inertia, 23% for cobbles and 20% for gravel pebble and bedrock.

Table 1: Simple CA on channel substrate types for 2680 semi-natural RHS in Great Britain. Only detailed results for the first 2 components are displayed. The 'Coord' columns contain the principal coordinates for each substrate type and axis. The 'Contr' column expresses the relative contribution of individual substrate types to axis definition whilst the 'Corr' column (or relative contribution) represents the amount of individual substrate inertia explained by each component (Greenacre, 1993).

240 Individual axes inertia relative to total inertia

	Axis	Inertia	Proportion	Cumula	ative				
	1	0.7767	0.2051	0.2051					
	2	0.6442	0.1701	0.3752					
	3	0.5991	0.1582	0.5334					
	4	0.5632	0.1487	0.6821					
	5	0.4317	0.1140	0.7961					
	6	0.4134	0.1092	0.9052					
	7	0.3589	0.0948	1.0000					
241	Total	3.7872							
242									
243	Colum	n Contribu	itions for con	nponents	1 and 2				
244	Component .1					mponent	2		
	Name	Coord	Corr	Contr	Coord	Corr	Contr		
	BE	0.793	0.190	0.097	-0.229	0.016	0.010		
	BO	0.835	0.307	0.151	-0.230	0.023	0.014		
	CO	0.511	0.226	0.097	-0.077	0.005	0.003		
	GP	-0.532	0.197	0.106	0.394	0.108	0.070		
	SA	-1.433	0.160	0.125	2.480	0.480	0.449		
	SI	-2.052	0.423	0.349	-2.119	0.451	0.449		
	CL	-2.008	0.097	0.074	-0.483	0.006	0.005		
	PE	0.067	0.000	0.000	0.039	0.000	0.000		
245									
246	Supple	mentary C	Columns		_				
247	Component 1			Component 2					
	Name	Coord	Corr	Contr	Coord	Corr	Contr		
	NV	-0.540	0.014	0.044	-0.084	0.000	0.001		
248									
249									
250	The fir	st CA axi	s represent	ted a grad	dual incre	ease in s	ubstrate siz	ze with a gradua	al shift
				-				-	
251	from sites dominated by fine sediment to sites dominated by larger substrate (Fig. 2). The								
252	second component represented a gradient between silt and sand dominated sites and								
253	explained nearly 50% of the inertias of both substrate types (Table 1). The remaining								
254	components either represented gradients between two or three substrate types or were								

linked to the occurrence of rare types such as peat or clay. Missing values were not
associated with any particular substrate category and only 1% of the missing values
inertia was explained by the first two components.



Fig. 1: Symmetrical plot of substrate category profiles for the first two CA axes.





²⁶³ The first component was chosen for its geomorphological relevance as it represented a

well-known dimension in sediment fining and sorting along the river network (Morris and

265 Williams, 1999) and has habitat significance with regards to species distribution

(Chessman et al., 2006; Gasparini et al., 1999; Rice et al., 2001). The CSI was calculated

²⁶⁷ for all existing RHS sites using channel substrate standard coordinates for the first

component in the following equation:

CSI = (0.89(AR+BE) +0.95 BO + 0.58 CO + 0.08 PE - 0.6 GP - 1.63 SA - 2.33 SI - 2.28
 CL) / N_{sc}

where each two-letter acronym refers to RHS channel substrate categories and N_{sc} is the
total number of spot-checks. Artificial channel substrate (AR) was given the same
coefficient as bedrock substrate.

3.2. Variable selection

275 Only attributes selected by the best subset procedure will be presented and discussed.

Land use categories and drift geologies were not selected in any of the models extracted

using the best subset procedure. The attributes retained for the analyses were the PCA

axes, solid geology age and categories and hydrometric areas.

279 The four PCA variables represent environmental gradients describing site location and

profile (PCA1; i.e. lowland low altitude and slope, and upland high altitude and slope),

catchment area (PCA2), local discontinuities in profile/geology (PCA3) and catchment

slope (PCA4) (Jeffers, 1998).

Solid geologies were split into two groups based on their age. More recent geologies from
the Permian and Triassic to the Neogene had significantly lower CSI values indicating
finer substrate types than geologies from the Carboniferous to the Precambrian (Fig. 3).
The geology age categories were recoded into one indicator variable coding for solid
geology ages younger than the Carboniferous (Fig. 4). Geology age distribution separates
Wales, Cornwall and part of the North and the Lake District from the lowland areas of
eastern and southern England.

Hydrometric areas were recombined into six groups based on their average CSI value 290 and ordered according to increasing substrate size. The distribution of hydrometric area 291 categories follows a pattern separating the uplands from the lowlands of England and 292 Wales (Fig. 5). Hydrometric area categories represent catchment size and its influence on 293 substrate with smaller hydrological units displaying coarser substrate types than larger 294 lowland catchments. Group 4, 5 and 6 represent steeper catchments with higher levels of 295 296 hill slope activity and reflect the preponderance of upland controls in the delivery of sediments. Catchments from the lower groups tend to have a higher proportion of 297 streams originating and running in low altitude low slope areas compared to higher 298

categories. Coarse sediment tends to originate closer to source and is linked to local
 erosion of hard rocks generally located in the upland areas. A lack of upland control within
 catchments is, therefore, likely to result in lower delivery of coarse sediments within the
 river system and a higher proportion of fine sediment arising from downstream attrition
 and fining (Werritty, 1992).





Fig. 3: One way Anova of CSI value against solid geology age categories derived from the 1979 BGS solid geological map for all RHS sites. Average CSI values per age category with 95% confidence intervals based on pooled standard deviation (*F*=819, p<0.0001, *n*=9934).

- 312 geological age and hardness. The first class contains recent erodible clay and limestone
- formations and displays rivers with predominantly fine sediment material. The following
- two solid geology classes comprise slightly older (Jurassic) soft sedimentary formations

³¹⁰ Solid geologies were grouped into eight classes based on increasing average CSI value

⁽Fig. 6). Upon examination, solid geology categories reflect two related aspects:

including chalk, clay, limestone, shales and marls that support streams dominated by fine 315 sediments with some occurrence of gravels and pebbles. Class three is dominated by 316 sedimentary sand, clay and Oolitic geologies. River channels running on those geologies 317 tend to display a higher fraction of gravels and pebbles with a lower predominance of fine 318 sediment. Solid geology class four is constituted of older and harder geologies from the 319 Carboniferous/Triassic period with sandstone and coal that support rivers with a 320 321 significantly higher occurrence of coarse substrate such as gravel-pebbles and cobbles and little fine sediment. Class five contains geologies from the Cambrian up to the 322 323 Carboniferous with a predominance of metamorphic and intrusive rocks such as grit stone and granite. Rivers running on these profiles tend to have coarser substrate with cobbles, 324 boulders and bedrock. Class six is constituted mainly of hard igneous and Palaeozoic 325 sedimentary rocks. These are associated with rivers showing a dominance of cobbles 326 with greater occurrence of boulders and bedrock. The last class represents Cambrian grit 327 and limestone rocks that are characterised by very coarse substrate types. 328 Geographically, harder and older geologies are located in the west of England, in Wales, 329 in the North West and near the Scottish border (Fig. 6). 330

From the previous three maps, we can observe spatial correlations between geological age, solid geology classes and hydrometric area categories. Although the three sets of variables are correlated, they each provide subtle differences in explaining substrate distribution.



Fig. 4: Solid geology age distribution in England and Wales from the 1:625,000 BGS solid geology map recombined into two classes. 'Recent geologies' represent geologies from the Neogene to the Triassic and 'older geologies' from the Carboniferous to the Precambrian.



Fig. 5: Hydrometric area category distribution in England and Wales. Categories from 1 to 6 represent hydrological units with increasing average CSI values for surveyed RHS sites. Low CSI values correspond to fine sediment dominated streams, high CSI to coarse sediment dominated streams.



- Fig. 6: Solid geology class distribution in England and Wales. Classes from 0 to 8
- represent solid geologies with increasing average CSI value for surveyed RHS sites. Low
- CSI values correspond to fine sediment dominated streams, high CSI to coarse sediment
- dominated streams.

351 3.3. Regression kriging

Following data quality checks, 9473 British RHS sites were retained for the analyses (Fig.
7A). The best model, following selection, included the four PCA axes, two solid geology
categories, geological age and four hydrometric area groups (Table 2). The model
explained 67% of the variability in CSI.



Fig. 7 : Distribution of A) 9473 RHS sites used for modelling CSI and B) 3884 sites used for testing.

The best fit for modelling the OLS and GLS residual variograms was obtained using a combination of spherical and exponential functions (Fig. 8). Spatial correlations were observable up to 5 km and started to plateau after 13 km. The presence of a nugget can be explained by between-surveyor variability as well as time of survey, flow condition etc. The residuals showed a slight tendency for under-prediction, but no great departure from

normality (Fig. 9A). Kriged residuals were added to the cross-validated linear model 364 predictions and the estimated R^2 for the spatially corrected model was 0.74. The kriged 365 model residuals showed a marked improvement in prediction with a tighter and more 366 symmetrical distribution around the mean and figures very close to zero (Fig. 9B). A 367 variogram plot of residuals following kriging showed no sign of remaining spatial 368 correlation. The kriged model residuals were also investigated for different years of 369 survey to check the validity of the model over time. The residuals showed no clear pattern 370 of change in distribution between the years of survey with most variability explained by 371 372 differences in sample size.

Table 2: OLS model linking transformed CSI values to GIS map-derived covariates following a best subset selection procedure.

Model Summary R² Adjusted R² RMSE Model R 1 0.818 0.670 0.669 1.103 373 Sum of Squares df Mean Square F р Regression 23345 2122.265 1743 < .001 11 Residual 11522 9466 1.217 Total 34867 9477 374 Standard Unstandardised Standardised t-value р Error intercept 5.978 0.029 209.358 < .001 PCA1 0.566 0.011 0.425 53.725 < .001 PCA2 0.443 0.011 0.262 39.218 < .001 PCA3 0.158 0.021 0.048 7.487 < .001 PCA4 0.062 0.028 0.015 2.240 0.025 Geological age -0.886 0.048 -0.231 -18.386 < .001 Solid Geology 2 < .001 0.301 0.038 0.073 7.831 Solid Geology 3 < .001 0.585 0.072 0.053 8.094 Hydrometric group 1 < .001 -1.525 0.072 -0.158 -21.032 Hydrometric group 2 -1.073 -23.284 < .001 0.046 -0.272 Hydrometric group 3 -0.558 -0.068 -9.075 < .001 0.062 Hvdrometric group 4 -0.540 0.032 -0.124 -16.712 < .001

The model was then tested on 3884 independent sites surveyed in 2006-11 mainly in England and Wales (Fig. 7B). The model explained 64% of the variability in the new data. The residual distribution was centred around zero and showed no tendency for over- or under-prediction (Fig. 9C). Histograms of residuals per year of survey showed no significant pattern.

The model and test data were then joined and the regression kriging model was applied to the entire river network. The resulting map (Fig. 10) shows a clear gradient between the uplands in the West and North of England and Wales dominated by harder, older geologies and coarser substrate types, and the East and South, where sedimentary rocks predominate and channels are dominated by finer sediments.



Fig. 8: OLS model residual variogram fitted with a combination of exponential and
spherical functions.



Fig. 9: Distribution of model residual values with fitted curves for the cross-validated GLS

linear regression model (A) before and (B) after kriging; and (C) for the test sample.



Fig. 10: Map of predicted values of CSI using regression kriging at every 500m across the 1:50,000 river network on a gradient from bedrock/boulder (blue) to gravel-pebble (green)

and silt-sand-clay (brown). White reflects areas of low drainage density where fewer
 streams are present.

397 4. Discussion

Using existing data and geostatistical modelling techniques, it was possible to identify and 398 predict channel substrate and apply the model to the entire river network in England and 399 Wales thus, providing environmental practitioners and managers with the first 400 comprehensive national scale map of channel substrate distribution across the network. 401 Traditionally, substrate is characterised using some quantification of sediment size 402 distribution; generally statistics taken from a distribution such as D₅₀ or D₈₄ (median size 403 or 84th percentile size). Sediment sizing is based on field survey where substrate is either 404 405 sampled manually or using mechanical techniques (Kondolf et al., 2003). Sampling efforts can be intensive and, therefore, expensive (Bunte et al., 2009) and there are no existing 406 407 national datasets of substrate size available at present. Davenport et al (2004) attempted to derive estimates of substrate size using RHS data. The Sediment Calibre Index (SCI) 408 was calculated by multiplying substrate occurrence by Wentworth category median size in 409 phi units and averaging over 10 spot-checks. We produced a modified version of the SCI, 410 the SCI_m by adding one category including bedrock and artificial substrate using the 411 following equation and correcting some of the mistakes that were introduced in the 412 original publication for sand and silt phi values (Angela Gurnell, pers. comm.): 413

414 SCI_m = (-12(AR+BE) - 8 BO - 7 CO - 3.5 GP + 1.5 SA + 6 SI + 9 CL) / N_{sc}

The SCI_m was applied to 10,135 RHS British sites and compared to the CSI. The correlation between the two indices was extremely high (Pearson correlation coefficient = -0.985, *n*=10,135) suggesting that the CSI and the SCI_m both represent average channel substrate size. It is important to note that CSI and SCI_m are unlikely to represent D₅₀

unless the substrate size distribution follows a unimodal symmetrical distribution. Further
studies involving comparisons with more traditional sediment sizing techniques and RHS
would help identify the relevance and significance of the CSI with regards to
characterising channel substrate across a 500 m reach but these data currently do not
exist.

424 One strong advantage of using multivariate techniques is in the identification of major patterns and dimensions that can be related to biological gradients of species distribution. 425 The assumption is that species distribution and community composition adapt to 426 dominant habitat gradients. In the present case, the main dimension extracted was a well-427 known substrate fining gradient (Werritty, 1992). Another advantage is that dominant 428 gradients are likely to be influenced by drivers of geomorphological change and are, 429 therefore, more predictable. CSI was correlated and explained by a series of attributes 430 acting at different scales that can be related to known drivers of geomorphological 431 change. At the local (site) scale, Jeffers' PCA1 and PCA3 represent ground slope whilst 432 PCA2 acts as a surrogate for discharge. Slope and discharge are the main drivers of 433 stream power which is strongly related to sediment transport and sorting (Rice and 434 Church, 1998). Solid geology classes and PCA4 provide a wider catchment scale context 435 of geomorphological influence on stream energy and sediment supply. The geology 436 categories reflect the age and hardness of geological types whilst PCA4 represents 437 upstream catchment slope (Jeffers, 1998). Wider scale influences were represented by 438 439 attributes such as geological age and hydrometric area groups that provided a greater spatial and climatic context for predicting channel substrate. 440

The geostatistical analysis of model residuals revealed the presence of remaining unexplained spatially correlated variance with a relatively short range. This suggests the presence of local random factors influencing substrate distribution, potentially linked to

sediment transport, sediment supply from the surrounding landscape (Church, 2002),

riparian land use or human-made impacts. They could also represent non-linear spatial

responses to geomorphic drivers or local discontinuities in substrate caused by

447 confluences, landslides/bank erosion or the presence of lakes or reservoirs (Rice et al.,

448 2001).

The kriging process greatly reduced the spatial correlation in the residuals and increased 449 the model predictive power. The model was also tested for its ability to predict substrate 450 for different surveys. Channel substrate and geomorphological forms tend to be quite 451 stable over decadal timescale and evolve slowly unless significant changes occur such as 452 channel modification or catastrophic events (Knighton, 1998). Therefore, we expected to 453 see no large decrease in predictive power across the years of survey. This was confirmed 454 for both the modelling and the test samples which showed very little deviation in 455 predictive power across survey years. 456

The overall predictive power of the model on the test sample was satisfactory with 64% of 457 the site variability explained by the model. An examination of model residuals for the 100 458 sites with the largest residual values showed no discernible patterns apart from under-459 prediction of artificial, bedrock (22 % of the sites) and peat substrates (2% of sites). Other 460 sources of error were investigated. For the 2007-8 RHS baseline survey, one third of sites 461 were surveyed on parts of the 1:50,000 river network not covered by the previous 462 sampling strategy which was based on the 1:250,000 river network. A comparison of 463 residual values between sites located on the 1:250,000 and 1:50,000 networks using 464 465 ANOVA showed a significant difference between sample means (F=384; p<0.001; n=2772). The model tended to predict slightly coarser substrate size on the 1:50,000 466 sample than observed. This could be linked to stream size and management regime. 467 Sites selected on the 1:50,000 sample tended to be narrower, with an average bankfull 468

width of 4.1 m (n=1692), compared to 9 m (n=3134) for the 1:250,000 sites, with a strong 469 presence of agricultural ditches and artificial channels. It is possible that the model 470 parameters do not fully account for small artificial channels and this shows some of the 471 limitations of using the predictive model on sites collected at different scales. The overall 472 impact of scale on predictive accuracy was, however, small and produced only a slight 473 decrease in overall predictive accuracy. A practical advantage of RK is that it honours 474 field data. Thus, predictions using RK will always fit perfectly the observed values at 475 surveyed sites. This is important from a predictive accuracy viewpoint, but also on an 476 477 operational viewpoint as it reinforces the credibility of the model in the eyes of users (Naura, 2014). 478

479 **5. Conclusion**

We proposed an alternative approach for mapping habitat elements across entire river 480 networks that makes use of existing semi-quantitative survey data, GIS map-based 481 covariate data and RK. A new national scale substrate index has been developed, which 482 is accurate from 500m up to national scales. This application shows the potential power of 483 using spatially explicit techniques for modelling river attributes at the national scale. The 484 analyses presented in this article are part of a broader effort to characterise and map river 485 habitats, identify river reaches for environmental management and develop practical tools 486 for impact assessment, diagnostics and management planning that will be demonstrated 487 in subsequent publications. 488

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