# A thermal-electrical analogy model of a four-floor building with occupancy estimation for heating system control \*

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Abstract: The well-known electrical analogy for thermal modelling is based on the observation that Fourier's equation for one dimensional heat transfer takes the same form as Ohm's law. This provides a system for creating and resolving complex heat transfer problems using an established set of physically–based equations. In this article, such a model is developed and evaluated for a four–floor modern university building. The model is represented in state space form for optimisation and simulation purposes. The electrical analogy is chosen so that the model can be extended and used for future research into distributed, demand–side control of multiple buildings on the university network, requiring a fast computation time. The estimation of occupancy, representing a significant internal heat source, is also investigated. Here, wifi usage and return  $CO_2$  data are combined in novel manner to improve the model response.

Keywords: thermal modelling; buildings occupancy; micro-climate; state space model.

#### 1. INTRODUCTION

The research behind this article ultimately concerns control system robustness and overall system optimisation, for the regulation of temperatures in buildings that are linked to a controllable external heating supply network. This is the case, for example, with the Lancaster University campus, for which a central energy centre supplies the hot water used to heat around 50% of the buildings. More generally, Heating, Ventilation and Air Conditioning (HVAC) systems have high energy requirements, hence there is considerable interest in the development of improved optimisation tools, micro-climate control algorithms and energy management systems. Examples include Price et al. (1999); Taylor et al. (2004); Yang and Wang (2013); Kim (2013); Goyal et al. (2013); Kossak and Stadler (2015); Uribe et al. (2015); Mayer et al. (2017); Gorni and Visioli (2017); Zhuang et al. (2018); Tate et al. (2018).

Numerous approaches for modelling heat transfer phenomena and energy use have been developed. The models obtained are commonly categorised into physically–based models and models that are statistically identified from data (Foucquier et al., 2013). Within this context, various zonal and multi–zone approaches exist. Of particular relevance to the present article, these include thermal models constructed using an analogy with electrical systems. This is based on the observation that Fourier's equation for one dimensional heat transfer takes the same form as Ohm's law. An early reference by Paschkis and Baker (1942) describes how components of a building are considered to store or resist heat flows, equivalent to capacitors and resistors in electrical systems (Ramirez-Laboreo et al., 2014).

This is useful as it provides a system for creating and resolving heat transfer problems using an established set of physically-based laws. Whilst page constraints preclude a full literature review here, relevant research includes e.g. multiple layered walls (Peng and Wu, 2008), heat exchanger networks (Chen et al., 2015), global building models (Fraisse et al., 2002), parameter estimation, optimal model order identification and model reduction (Penman, 1990; Gouda et al., 2002; Goval and Barooah, 2012). Relatively high order resistor-capacitor (RC) networks are sometimes employed in order to model building components. For example, Peng and Wu (2008) represent a wall consisting of multiple layers of materials with air gaps, as a system with three resistors and one capacitor (denoted 3R1C). However, as a greater number of zones are modelled concurrently, the network diagrams can become very large. In such cases, programs such as TRNSYS (Klein et al., 1978) are used to collate the models.

The present article considers the freestanding Charles Carter Building, in the south part of Lancaster University's main campus. The electrical analogy is chosen so that the models obtained can be straightforwardly extended and used for future research into demand-side control (Kim, 2013) of multiple buildings on the university network, requiring a fast computation time for energy optimisation purposes. With this objective in mind, the models should be simple to construct and implement, initially using readily available physical parameters, such as room dimensions and estimates of thermal resistance. Nonetheless, since the University's Building Management System (BMS) includes comprehensive data collection for many parts of campus, the model is optimised directly from data where possible, using the physically-based parameters as initial conditions.

<sup>\*</sup> This work is supported by Engineering and Physical Sciences Research Council (EPSRC): EP/M015637/1.

Analysis of the initial model highlights a limitation, namely the lack of a suitable internal heat source to represent changing occupancy rates. The rooms are office spaces, hence human occupancy and electrical equipment will contribute heat (Luo et al., 2018; Tabak and de Vries, 2010; Yang and Becerik-Gerber, 2014). As a result, the model is extended to include occupancy estimated using data on (floor by floor) wifi usage and  $\rm CO_2$  levels (associated with each of the air handling units) in the Charles Carter Building. The new model is expressed in state–space form and evaluated at full building scale.

## 2. CASE STUDY

Lancaster University campus has several recently constructed buildings fully instrumented with a range of sensors and actuators, and seems well suited for research into the optimisation of energy efficiency because of the associated BMS data collection capacity. The architects of the Charles Carter Building, for example, integrated various energy—reducing features into the building design, which achieved a BREEAM Excellent rating. The south elevation is designed to shade the building while the concrete roof protects the top floor from heating up in the sun. The building footprint is 33 m by 36 m, while there are four floors (A–D), as illustrated by Fig. 1. Internally the building is laid out around a central atrium that is open from the floor to the roof. Surrounding this area are lecture theatres, offices, meeting rooms and break-out spaces.

Micro-climate data are collected by the BMS every 10 minutes including, for example, the supply and return air temperatures for various rooms, ventilation power levels and HVAC set points. For purpose of the present article, the main occupied rooms are represented as 16 zones in Fig. 1, each representing an individual Air Handling Unit (AHU) with measured 'return' air temperature  $T_i(t)$  (i = 1, ..., 16). Illustrative temperature measurements are shown for two such zones in Fig. 2 (degrees Celsius, °C).

# 3. MODEL FORMULATION

The model is expressed in conventional continuous-time state space form, as follows,

$$\dot{\boldsymbol{x}}(t) = \mathbf{A}\boldsymbol{x}(t) + \mathbf{B}\boldsymbol{u}(t)$$
$$\boldsymbol{y}(t) = \mathbf{C}\boldsymbol{x}(t) + \mathbf{D}\boldsymbol{u}(t)$$
 (1)

where  $\mathbf{y}(t)$  is a  $16 \times 1$  vector of output variables, i.e. the temperature  $T_i(t)$  in each zone and  $\mathbf{u}(t)$  is a  $34 \times 1$  vector of input variables, with elements  $u_i(t)$  (section 3.1). In the physically-based model developed below,  $\mathbf{C}$  is an identity matrix and  $\mathbf{D} = \mathbf{0}$  is a matrix of zeros, hence the state vector  $\mathbf{x}(t) = \mathbf{y}(t)$ . Finally,  $\mathbf{A}$  and  $\mathbf{B}$  are matrices with elements  $a_{ij}$   $(i,j=1,\ldots,16)$  and  $b_{ij}$   $(i=1,\ldots,16,j=1,\ldots,34)$  respectively (see sections 3.2 and 3.3).

#### 3.1 Heat inputs

The total heat input to each zone,  $q_i(t)$  (i = 1, ..., 16) (W), consists of three components as follows,

$$q_i(t) = \epsilon_i(t) + \gamma_i(t) + \zeta_i(t) \tag{2}$$

where  $\epsilon_i(t) = h_i c_p^a \dot{m}_i(t) \delta T_i(t)$  is the controlled heat flow from the AHU (either cooling or heating),  $\gamma_i(t) = (\omega +$   $\sigma_i)g_i(t)$  is an internal heat source and  $\zeta_i(t) = \phi_i M(t)$  is the heat supplied from the campus hot water heating system.

Here,  $c_p^a$  is the the specific heat capacity of air;  $\dot{m}_i(t)$  is the mass flow of the air handling unit in zone i (m³ s<sup>-1</sup>);  $\delta T_i(t) = S_i(t) - T_i(t)$  is the temperature difference between the supply and return air, in which  $S_i(t)$  is the inlet air temperature; and  $h_i = 0.9 \,\forall i$  (initial assumption, prior to optimisation) is an empirical mixing coefficient, introduced since not all of the incoming air mass will be fully mixed before it is extracted at the outlet. The mass flow is not directly measured and so is determined as follows,

$$\dot{m}_i(t) = f\rho_a r_i(t) \tag{3}$$

where  $f=0.006~{\rm m}^6~{\rm kg}^{-1}$  is a fan properties coefficient, representing the effective diameter and pitch,  $\rho_a$  is the air density and  $r_i(t)$  represents the fan RPM/60 i.e. revolutions per second. Hence,  $\epsilon_i(t)=\left(h_i~c_p^a~f\rho_a\right)\cdot r_i(t)\cdot\delta T_i(t)$ , which is bilinear in  $r_i(t)$  and  $\delta T_i(t)$ , and a function of the zone temperature, raising identifiability challenges that are the subject of current research by the authors.

With regard to the internal heat source,  $g_i(t)$  represents the time–varying number of occupants in each room, while  $\omega=100~\mathrm{W}$  is based on an assumed average heat output per person (Luo et al., 2018). The additional heat gain coefficients  $\sigma_i=10~\mathrm{W}$  for  $i=1,\ldots,5$  and  $\sigma_i=50~\mathrm{W}$  for  $i=6,\ldots,16$  are associated with electronic equipment. These initial values (prior to optimisation) are based on an assumption that Floor A is primarily used for teaching, whilst on floors B–D staff utilise desktop computers.

In  $\zeta_i(t)$ , M(t) represents the heat supplied by hot water entering the building from the campus-wide heating system (W), while the proportion of this heat that reaches a particular zone is denoted  $\phi_i$ . There are a number of data collection limitations associated with these terms, hence they are the subject of on-going research. For the purpose of the present article, 50% of the heat is assumed to reach the modelled zones, and  $\phi_i$  is initially assumed to be split equally between these zones, hence  $\phi_i = 0.03 \,\forall i$  (retaining the index since this coefficient can potentially be optimised from data for each zone i).

To represent these heat inputs via equations (1), the first sixteen elements of u(t) are defined  $u_i(t) = g_i(t)$  (i = 1, ..., 16), i.e. the number of occupants; and the next sixteen elements,  $u_j(t) = r_i(t) \delta T_i(t)$  (j = 17, ..., 32; i = 1, ..., 16) are the input signals associated with the controlled heat flow from each AHU. Finally,  $u_{34}(t) = M(t)$ , while  $u_{33}(t) = T_E(t)$  is an additional exogenous variable, namely the outdoor temperature. The various time–invariant coefficients alluded to above are embedded in  $\bf A$  and  $\bf B$ , defined from first principles or estimated from data, as discussed below.

#### 3.2 Heat balance equations

The thermal model for each zone consists of a first order differential equation, analogous to a RC network. In the analogy, R is the thermal resistance of the walls and C is the capacitance of the constituent material. As the intention is to formulate a simple model, a 1R1C system is initially assumed for each room. To illustrate the principle,

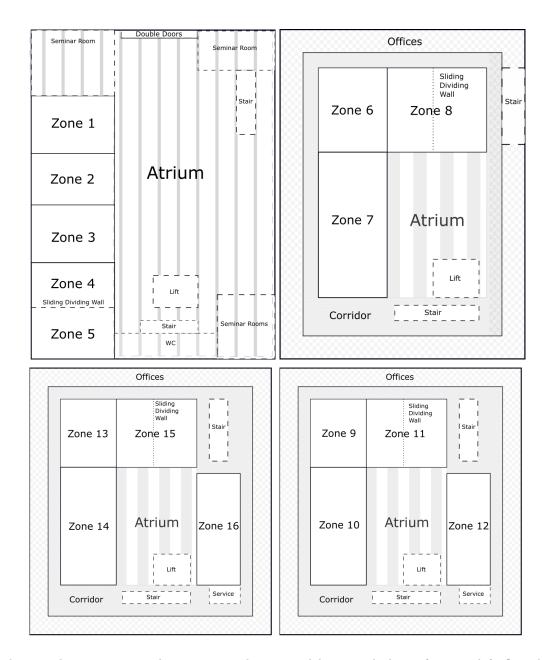


Fig. 1. Floor layouts showing zone numbers corresponding to model states: clockwise from top left, floor A, B, C and D.

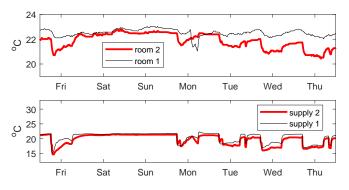


Fig. 2. Illustrative room (return) and supply (air conditioning) temperatures, Friday 1st to 7th Sept. 2017.

consider the temperature  $T_2(t)$  for zone 2 on A-floor. The temperature in this zone is coupled to the adjacent zones 1 and 3, with temperatures  $T_1(t)$  and  $T_3(t)$ , and  $T_6(t)$  above on B–floor. Hence, assuming heat capacity  $C_2$  and walls/floors of thermal resistance  $R_{1,2},\,R_{2,3},\,R_{2,6}$  and  $R_{2,E}$ , standard heat balance equations yield,

$$q_{2}(t) = C_{2} \frac{dT_{2}(t)}{dt} + \frac{T_{2}(t) - T_{1}(t)}{R_{1,2}} + \frac{T_{2}(t) - T_{3}(t)}{R_{2,3}} + \frac{T_{2}(t) - T_{6}(t)}{R_{2,6}} + \frac{T_{2}(t) - T_{E}(t)}{R_{2,E}}$$
(4)

in which  $q_2(t)$  represents the total heat flow (2). Rearranging to isolate the relevant state yields,

$$\frac{dT_2(t)}{dt} = \frac{q_2(t)}{C_2} + \frac{T_1(t)}{C_2 R_{1,2}} + \frac{T_3(t)}{C_2 R_{2,3}} + \frac{T_6(t)}{C_2 R_{2,6}} + \frac{T_E(t)}{C_2 R_{2,E}} - \frac{T_2(t)}{C_2} \left[ \frac{1}{R_{1,2}} + \frac{1}{R_{2,3}} + \frac{1}{R_{2,6}} + \frac{1}{R_{2,E}} \right]$$
(5)

Noting that  $u_2(t) = g_2(t)$  and  $u_{18}(t) = r_2(t)\delta T_2(t)$ , equation (5) is represented in the state space model (1), by defining the following elements for **A** and **B**,

$$a_{2,2} = -\frac{1}{C_2} \left[ \frac{1}{R_{1,2}} + \frac{1}{R_{2,3}} + \frac{1}{R_{2,6}} + \frac{1}{R_{2,E}} \right]$$
 (6)

$$a_{2,1} = \frac{1}{C_2 R_{1,2}} \; ; \; a_{2,3} = \frac{1}{C_2 R_{2,3}} \; ; \; a_{2,6} = \frac{1}{C_2 R_{2,6}}$$
 (7)

$$b_{2,2} = \frac{\omega + \sigma_2}{C_2} \; ; \; b_{2,17} = \frac{h \; c_p^a \; f \rho_a}{C_2}$$
 (8)

$$b_{2,33} = \frac{1}{C_2 R_{2,E}} \; ; \; b_{2,34} = \frac{\phi_2}{C_2} \quad (9)$$

The remaining elements on the second row of **A** and **B** are zero. Similar 1R1C models are developed for each zone of the building and embedded in (1).

# 3.3 Physically-based parameters

Initial values for the model coefficients are obtained by mechanistic considerations, as detailed below. The thermal capacitance of each zone (i = 1, ..., 16), summarised in Table 1, is the sum of the capacitance associated with the air, room objects (e.g. furniture) and walls, as follows,

$$C_i = C_i^a + C_i^f + C_i^w (10)$$

where  $C_i^a = V_i^a \ \rho_a \ c_p^a, C_i^f = V_i^f \ \rho_f \ c_p^f$  and  $C_i^w = V_i^w \ \rho_w \ c_p^w$ , in which  $V_i^a$  is the volume of the air in the zone,  $V_i^f$  is the volume of objects in the zone and  $V_i^w$  is the volume of the walls/floor/ceiling surrounding the zone. In a similar manner,  $\rho_a$ ,  $\rho_f$  and  $\rho_w$  are the respective densities, whilst  $c_p^a$ ,  $c_p^f$  and  $c_p^w$  are the specific heat capacities.

Here, air density  $\rho_a=1.225~{\rm kg~m^{-3}}$  and air specific heat capacity  $c_p^a=1.005~{\rm kJ~kg^{-1}~K}$  are taken as homogeneous across the building, since the properties of air change very little within a realistic temperature range e.g.  $c_p^a=1.013~{\rm kJ~kg^{-1}~K}$  at  $150^{\circ}C$ . The density and specific heat capacity of objects and walls are initially assumed  $\rho_f=\rho_w=1000~{\rm kg~m^{-3}}$  and  $c_p^f=c_p^w=0.9~{\rm kJ~kg^{-1}~K}$  respectively.

Bespoke room volumes  $V_i^a$   $(i=1,\cdots,16)$  are determined from the building layout, whilst  $V_i^f$  (the volume of carpets, furniture, etc.) is initially assumed to be in the region of 1–2 m<sup>3</sup>. Finally, the wall volumes are,

$$V_i^w = \sum_{p=1}^n \frac{d_p}{2} l_p h_p \tag{11}$$

where n is the number of walls (usually 6 including floor and ceiling),  $d_p$  is the wall depth (0.01–0.2 m), halved as it assumed that half the volume is included in each zone,  $l_p$  is the length (5–10 m) and  $h_p$  height (3 m). Using these values, the heat capacitance of room objects and walls are 1000–2000 J K<sup>-1</sup>, which fits with expected values from the literature e.g. Wolisz et al. (2015).

Wall thermal resistances are based on,

$$R_{i,j} = \frac{d_{i,j}}{\lambda_{i,j} A_{i,j}} \tag{12}$$

Table 1. Thermal capacitance.

Physical Parameters									
i	$V_i^a$	$V_i^f$	$V_i^w$	$C_i^a$	$C_i^f$	$C_i^w$	$C_i$		
1	165	2	3	203	1800	2700	4703		
2	165	2	3	203	1800	2700	4703		
3	165	2	3	203	1800	2700	4703		
4	154	1.5	2.5	190	1350	2250	3790		
5	154	1.5	2.5	190	1350	2250	3790		
6	97	1	1	119	1800	2700	4703		
7	194	2	1	239	1800	900	2939		
8	73	1	1.5	90	900	1350	2340		
9	97	1	1	119	1800	2700	4703		
10	194	2	1	239	1800	900	2939		
11	73	1	1.5	90	900	1350	2340		
12	243	2	0.5	300	1800	450	2550		
13	97	1	1	119	1800	2700	4703		
14	194	2	1	239	1800	900	2939		
15	73	1	1.5	90	900	1350	2340		
16	243	2	0.5	300	1800	450	2550		

where  $d_{i,j}$  is wall depth (m),  $\lambda$  thermal conductivity (W/km) and  $A_{i,j}$  wall area (m<sup>2</sup>), with the indices representing the relevant zone numbers. The wall depth is typically 0.01–0.02 m for glass panels and 0.03–0.08 m for the internal walls. Composite walls are modelled using their 'U' value, i.e. the thermal transmittance, which is the sum of reciprocals of the resistances of the wall elements, also including convection and radiation from the internal and external surfaces. The relevant calculations are developed using U–value conventions from Anderson (2006).

Hence, using units of K W<sup>-1</sup> throughout, the resistance of the outer offices to the external temperature on floors B–D is  $R_{i,E}=37.2$  ( $i=6,\cdots,16$ ), whilst the glass panels on A floor yield  $R_{i,E}=0.1$  ( $i=1,\cdots,6$ ). Internal walls of gypsum and celcon yield  $R_{1,2}=R_{2,3}=R_{3,4}=R_{6,8}=R_{9,11}=R_{13,15}=0.4$ . The resistance of floors is dominated by an air gap, yielding  $R_{1,6}=R_{2,6}=R_{3,7}=R_{4,7}=R_{5,7}=R_{6,9}=R_{6,10}=R_{7,10}=R_{8,11}=R_{9,13}=R_{10,14}=R_{10,15}=R_{11,12}=R_{11,15}=R_{11,16}=R_{12,16}=1.0$ . Finally,  $R_{4,5}=0.01$ ,  $R_{6,7}=R_{9,10}=R_{13,14}=0.05$  and  $R_{10,12}=R_{11,12}=R_{14,15}=R_{15,16}=0.8$ .

### 4. OCCUPANCY ESTIMATION

In the simplest case,  $\gamma_i(t)$  in equation (2) is either based on assumed average occupancy rates or as a set of arbitrary coefficients to be optimised from the temperature measurements (together with all the other parameters). Alternatively, the model is potentially improved by explicitly addressing how the occupancy levels vary over the course of the day in different parts of the building. Unfortunately occupancy is not normally measured directly. Hence, two sets of data gathered by the BMS are combined to provide estimates: the number of devices connected to the wifi hubs and the returning  $\mathrm{CO}_2$  levels.

There are four wifi hubs in the Charles Carter Building, one per floor, which log the total number of connected devices every 10 minutes. This aspect of the estimate assumes that everyone posses a wifi connected device, and doesn't account for individuals possessing two devices e.g. a smart phone and laptop. However, as the staff and research student offices have desktop PCs with a wired connection, one device per person seems a reasonable initial approximation. Furthermore, this somewhat simplistic

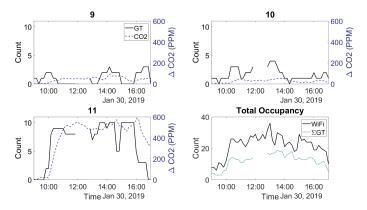


Fig. 3. Observed (GT: ground truth) occupancy and change from minimum CO<sub>2</sub> level on C-floor for zones 9, 10 and 11; and (lower right subplot) total C-floor observed occupancy and C-floor wifi data.

approach is appealing since existing sensors and readily available data sets are used i.e. there is scope for general implementation throughout the university, without requiring the installation of bespoke sensors.

However, since there is only one wifi hub per floor, this count provides no insight into to how the occupants are distributed between different rooms or zones on the floor. The latter is provided by the relative changes in  $CO_2$  levels. To illustrate the approach, the occupancy  $g_i(t)$  for the four zones on C-floor are estimated using,

$$g_i(t) = P_c(t) \frac{H_i(t+b) - min(H_i)}{\sum_{i=1}^4 (H_i(t+b) - min(H_i))}$$
(13)

where  $P_c(t)$  is the total number of occupants on C-floor as recorded by the wifi hub,  $H_i(t)$  the CO<sub>2</sub> level (ppm) and b is the time-delay. For a preliminary evaluation, 'ground truth' measurements were taken by the present first author every 10 minutes during a week day in both a university holiday (25th Sept. 2018) and during term-time (30th Jan. 2019). As illustrated by Fig. 3, the wifi hub data generally conforms to the real occupancy trend, albeit with consistent over-estimation. This offset is addressed by suitable estimation of  $\omega$  and  $\sigma_i$ . The lower-left plot of Fig. 3 clearly displays that an appreciable rise in CO<sub>2</sub> level is associated with an increase in the number of occupants. Hence, there is evidence that CO<sub>2</sub> and wifi data provide an indication of occupancy, sufficient at least to subsequently yield good estimates of the temperature response, as demonstrated in the following section.

# 5. RESULTS

The elements of the transition matrix **A** and matrix **B** of the state space model (1) relate to the physical properties of the zone. In this case, the system matrices also include numerous zero elements e.g. where there is no wall, ceiling or floor linking two rooms. One limitation of this method is that it ignores relatively small but sometimes potentially significant coupling effects e.g. most zones in the building share a wall with the central atrium. Hence, for improved model performance, selected composite parameters are numerically optimised from the available data. To illustrate, MATLAB ssest is utilised for iterative parameter

Table 2. RMSE for: (i) constrained optimisation, (ii) constrained optimisation with initial conditions based on physical coefficients, (iii) unconstrained optimisation of  $[\mathbf{A}, \mathbf{B}]$  and (iv) optimisation of  $\mathbf{B}$  only.

Zone	(i) Const.	(ii) Init.	(iii) Free	(iv) Opt. B
1	10.05	4.99	0.44	1.12
2	10.49	5.61	0.47	1.09
3	10.27	5.62	0.40	1.14
4	9.85	5.69	0.39	0.99
5	8.33	4.28	0.66	1.03
6	11.15	6.38	0.44	1.22
7	11.10	6.30	0.42	1.25
8	9.70	5.46	0.56	1.02
9	11.46	6.47	0.55	1.22
10	11.05	6.09	0.57	1.29
11	9.84	5.53	0.77	1.17
12	10.32	5.89	0.42	1.11
13	10.36	6.28	0.43	1.19
14	10.41	6.13	0.40	1.13
15	10.24	5.93	0.44	1.09
16	10.00	5.82	0.41	1.09

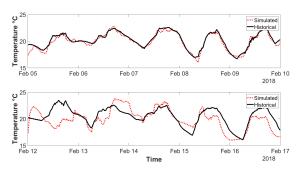


Fig. 4. Measured temperatures (solid) compared to the optimised model response (dotted) for an illustrative AHU on A-floor for the first week of February 2018. Upper plot: estimation. Lower: validation experiment.

estimation via a subspace Gauss–Newton or Levenberg–Marquardt least squares search. Figure 4 illustrates a typical model fit when using unconstrained optimisation of [A,B] in this manner, with column (iii) of Table 2 showing the Root Mean Square Errors (RMSE) between the simulated and actual return temperatures. Here, if the purely mechanistic model is utilised the fit is very poor, hence Table 2 only summarises the results for various optimisation approaches: column (i) uses zero for the coefficient initial values, whilst (ii) utilises the physically–based values of the coefficients developed in section 3.3, demonstrating the value of determining these.

Although yielding the lowest RMSEs in Table 2, completely free optimisation can yield unsuitable coefficients for when the model is applied to other scenarios in validation experiments. In this regard, preliminary analysis suggests that a hybrid approach in which only **B** is optimised yields the best performance overall. Finally, although details are omitted for brevity, the introduction of the occupancy estimates can yield an improved fit compared to an assumed time-invariant internal heat, although this requires further research.

#### 6. CONCLUSIONS

A model of a four-floor building on a university campus has been developed using the thermal–electrical analogy. Physically-derived parameters yield relatively poor performance, which is improved when the model is combined with occupancy estimation and numerical optimisation of the coefficients using data from the BMS. In this regard, one novelty of the proposed approach is the utilisation of occupancy estimates based on a bespoke combination of wifi and  ${\rm CO}_2$  data. However, to validate the approach and to compare with other modelling methods from the literature, additional observation days are required and this is the subject of current research by the authors.

An energy centre provides hot water for heating the building, and contains multiple methods of heat production, such as gas boilers and a biomass generator. Therefore, in future research, this type of model will be used to explore options for a hierarchical control system, with a particular focus on optimising the use of the boilers and generator. In this regard, the authors are presently developing demandside control concepts to address multiple buildings on the network i.e. the control actions for one building are accounted for when choosing actions for the other buildings. This will be achieved within a non-minimal state space model predictive control framework (Taylor et al., 2013). Moreover by incorporating weather into the control system and so making full use of the available data from the local Hazelrigg weather station, it is anticipated that the entire network can be better optimised.

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