Isotropic Brownian motions over complex fields
as a solvable model for May–Wigner stability analysis

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Abstract

We consider matrix-valued stochastic processes known as isotropic Brownian motions, and show that these can be solved exactly over complex fields. While these processes appear in a variety of questions in mathematical physics, our main motivation is their relation to a May–Wigner-like stability analysis, for which we obtain a stability phase diagram. The exact results establish the full joint probability distribution of the finite-time Lyapunov exponents, and may be used as a starting point for a more detailed analysis of the stability-instability phase transition. Our derivations rest on an explicit formulation of a Fokker–Planck equation for the Lyapunov exponents. This formulation happens to coincide with an exactly solvable class of models of the Calgero–Sutherland type, originally encountered for a model of phase-coherent transport. The exact solution over complex fields describes a determinantal point process of biorthogonal type similar to recent results for products of random matrices, and is also closely related to Hermitian matrix models with an external source.

1 Introduction

A close link between stochastic calculus and random matrix theory exists since the seminal work of Dyson [1], who introduced a stochastic process on matrices which greatly simplifies the task to implement various canonical ensembles. Since its introduction, this method, now known as Dyson Brownian motion, has found a wide variety of applications in both physics and mathematics, see e.g. [2]. Two important examples of matrix-valued stochastic models in physics concern the passive advection in fully developed turbulence [3, 4, 5, 6, 7, 8, 9], where one is interested in the stability of the flow, and the phase-coherent transport through disordered wires [10, 11, 12, 13, 14, 15, 16, 17], where one encounters Anderson localization. While Dyson’s model has additive noise, these models have multiplicative noise, which gives rise to scaling regimes with statistics that differ from the usual Wigner–Dyson type. Not surprisingly, there are numerous close connections between these two classes of models with multiplicative noise [18, 19].

In this work, we identify a similarly close relation starting from a paradigmatic model, sometimes referred to as isotropic Brownian motions [5], isotropic stochastic flows [6], or matrix-valued multiplicative diffusions [20]. For motivation, we consider this model in the context of a May–Wigner-like stability analysis of large complex systems, as they occur in a wide variety of settings in physics, biology and beyond. We show that the finite-time Lyapunov exponents share the same statistics as those appearing in the transport through a quantum wire with chiral symmetry. This connection is surprising inasmuch as the exponents for the quantum wire are constrained by a condition related to flux conservation, which does not have a counterpart for the isotropic Brownian motion. The relation between the models allows
us to find an exact solution for motions over complex fields, owing to the fact that the statistics in
the corresponding transport problem is determined by a Hamiltonian of the Calgero-Sutherland type. 
Furthermore, we identify connections to products of random matrices, including Newman’s square law [21] 
and biorthogonal ensembles [22, 23], as well as Hermitian matrix models with an external source [24, 
25, 26]. These findings help us to establish a simple stability phase diagram, expressed in terms of an 
effective parameter that incorporates the rotational and gradient components of the flow, and defines a 
convenient starting point for more detailed investigations of the phase transition.

First, let us recall some basics about May–Wigner-like stability analysis. We consider a generic 
autonomous dynamical system given by

\[ \frac{dy_i(t)}{dt} = f_i(y_1(t), \ldots, y_N(t)), \quad i = 1, \ldots, N, \]  

where \( \{f_i\} \) is some family of smooth functions and the dimension \( N \) is assumed to be large. Introducing 
a small perturbation \( y(t) \mapsto y(t) + \varepsilon \tilde{y}(t) \) leads to the linearised problem

\[ \frac{d\tilde{y}_i(t)}{dt} = \sum_{j=1}^{N} \tilde{y}_j(t) \frac{\partial f_i}{\partial y_j} + O(\varepsilon). \]  

If the expansion is about a fixed point the gradient matrix \( \frac{\partial f_i}{\partial y_j} \) is independent of time. It is then 
canonical to write \( \frac{\partial f_i}{\partial y_j} = -\mu \delta_{ij} + \sigma J_{ij} \), where \( J_{ij} \) incorporates the coupling between \( \tilde{y}_i \) and \( \tilde{y}_j \), while \( \sigma \) sets an overall coupling strength and \( \mu \) sets a drift which for positive values may be interpreted as the 
relaxation rate at \( \sigma = 0 \).

For sufficiently complex systems it is reasonable to assume (at least as a toy model) that \( J = [J_{ij}] \) is 
a “maximally random” matrix, up to symmetries stemming from physical considerations. Such models 
were introduced in a seminal paper by May [27]. The original paper was mainly focussing on the stability 
of large ecosystems, where it challenged the (at the time) common folklore that the stability of complex 
systems increases with the size of the system. Similar ideas as those introduced in [27] have since been 
applied to many other systems, including e.g. machine learning [28], finance [29], and neural networks [30]. 
There is also a close connection to what is known as random landscapes [31, 32, 33].

Rather than an expansion around a fixed point, we imagine to evaluate the gradient matrix along a 
trajectory, see e.g. [19]. In this case, the gradient matrix depends on the position on the trajectory and 
therefore indirectly on time. With May’s model in mind, we write

\[ \frac{d\tilde{y}_i(t)}{dt} = \sum_{j=1}^{N} (-\mu \delta_{ij} + \sigma J_{ij}(t))\tilde{y}_j(t) \]  

with some time-dependent coupling matrix \( J_{ij}(t) \), to be further specified below. This is such that we have 
an attractive trajectory with relaxation rate \( \mu \) when the coupling strength vanishes, i.e. when \( \sigma = 0 \). 
Our main assumption is that the time-dependent coupling \( J_{ij}(t) \) can be treated as noise, which we let 
be white in time. Such an approximation is valid in the limit of strong chaoticity, where the correlation 
time is short.

We therefore consider the system (3) driven by Gaussian white noise, with the only constraint that 
the system must be isotropic. Originally, this type of process arose in models for passive advection in 
fully developed turbulence (here isotropy appears as an axiom stemming from K41 theory), see e.g. [4, 9]. 
The insight that temporal correlations may be neglected for turbulent velocity fields in the limit of high 
Reynolds numbers dates back to Kraichnan [34]. This type of isotropic models has also been considered 
by the mathematical community, see e.g. [5, 21, 6, 35]. Later methods originating from random matrix 
theory and quantum field theory have been applied as well [20, 8].

We recall that the white-noise limit of processes like (3) depends on the regularisation (the one-
dimensional case, which is a geometric Brownian motion, provides a well-known example). Thus one
needs to choose an interpretation, or alternatively impose additional constraints (see e.g. the appendix in [9]). For consistency with the existing literature [5, 21] we choose the Stratonovich interpretation as our starting point,

\[ d\tilde{y}_i(t) = -\mu \tilde{y}_i(t)dt + \sigma \sum_{j=1}^{N} \tilde{y}_j(t) \circ dB_{ij}(t), \quad i = 1, \ldots, N, \]

(4)

where \( B(t) = [B_{ij}(t)] \) is a matrix-valued Brownian motion assumed to be statistically invariant under unitary similarity transformations. This is the type of process that we refer to as isotropic Brownian motion.

For the practical implementation, on the other hand, it will be convenient to work in Itô convention, in which the process (4) becomes

\[ d\tilde{y}_i(t) = -\mu \tilde{y}_i(t)dt + \sigma \sum_{j=1}^{N} \tilde{y}_j(t)dB_{ij}(t) + \frac{1}{2}\sigma^2 \sum_{j,k=1}^{N} \tilde{y}_j(t)\mathbb{E}[dB_{ik}(t)dB_{kj}(t)]. \]

(5)

We recall that formally \( \mathbb{E}[dB_{ih}(t)dB_{kj}(t)] \propto dt \). We note that the difference between Stratonovich and another interpretation (such as Itô) is merely an additional spurious drift term which, in principle, could be absorbed into the constant \( \mu \).

Before we go on to the main results of this paper, let us recall a few basic properties of isotropic Brownian motions. Given an initial condition \( y(0) \), the solution to the system (5) may in matrix notation be written as

\[ y(t) = \Pi_\mu(t)y(0), \]

(6)

where \( \Pi_\mu(t) \) is a random evolution matrix, which itself satisfies an Itô equation similar to (5),

\[ d\Pi_\mu(t) = (-\mu dt + \sigma dB(t) + \frac{1}{2}\sigma^2 \mathbb{E}[dB(t)dB(t)])\Pi_\mu(t), \]

(7)

with initial condition \( \Pi_\mu(0) = 1 \). Moreover, with \( \Pi(t,s) \) denoting the evolution from time \( s \) to time \( t \), we have the almost-sure property \( \Pi_\mu(t,s)\Pi_\mu(s,0) = \Pi_\mu(t,0) \) for all \( t \geq s \geq 0 \). Per definition, the solution is given as an ordered product,

\[ \Pi_\mu(t) = \lim_{n \to \infty} \prod_{k=1}^{n} (1 + (\mu + \frac{1}{2}\sigma^2 \mathbb{E}[X^{(k)}^2])dt + \sigma X^{(k)}\delta t^{1/2}));, \]

(8)

where \( \delta t := t/n \) is the time regularisation and \( \{X^{(k)}\} \) is a family of independent random matrices given as the Brownian increments, \( X^{(k)}\delta t^{1/2} = B(k\delta t) - B((k-1)\delta t) \). We could, of course, also write the random evolution matrix as a time-ordered exponential, but we will not need that formulation here. It follows that finding the random evolution matrix (5) boils down to evaluating a product of independent random matrices; a topic which in the discrete setting has received considerable recent attention [36, 37, 38, 39, 40, 41, 42].

In this paper, we consider evolutions over real as well as complex vector fields; thus, the random matrix \( X = X^{(k)} \) may be either real or complex. Adopting notation from random matrix theory, the real and complex case will be denoted by an index \( \beta = 1 \) or \( \beta = 2 \), respectively, whenever the distinction is important.

Isotropy implies that \( U^{-1}XU \overset{d}{=} X \) for all rotations \( U \), i.e. \( U \in O(N) \) for \( \beta = 1 \) and \( U \in U(N) \) for \( \beta = 2 \). Up to a shift proportional to the identity, the most general matrix \( X \) consistent with the isotropy constraint and Gaussianity is a matrix from the Gaussian elliptic ensemble (see appendix A), i.e. a random matrix distributed with respect to the density [43]

\[ P^\beta_\tau(X) = \frac{1}{Z} \exp \left[ -\frac{\beta}{2(1-\tau^2)} \text{Tr} \left( XX^\dagger - \frac{\tau}{2} (X^2 + X^\dagger 2) \right) \right], \]

(9)
with $Z$ denoting the normalisation constant and $\tau \in (-1, 1)$ denoting an interpolation parameter between Hermitian and skew-Hermitian matrices. In general, the matrix $X$ is non-Hermitian (Ginibre for $\tau = 0$) and the random evolution matrix $\Pi_{\mu=0}(t)$ is therefore a diffusion on the general linear group, $\text{GL}_N$. The special case is $\tau = -1$, where $X$ is skew-Hermitian and thus $\Pi_{\mu=0}(t)$ belongs to the unitary subgroup. Physically $\tau$ measures the rotational versus gradient nature of the flow, with $\tau = 1$ representing a pure gradient flow.

Perhaps the simplest question we may ask about isotropic Brownian motions regards the large-time asymptotic of the strain matrix, $S(t) := \Pi_{\mu=0}^t(t)\Pi_{\mu=0}(t)$. It is a well-known consequence of Oseledec’s multiplicative ergodic theorem [44] that the matrix $(\log S(t))/2t$ stabilises for almost all realisations as $t$ tends to infinity. The eigenvalues of this limiting matrix are the so-called Lyapunov exponents and are used as a measure of stability. A system (4) is said to describe an attractive trajectory if

$$\|\tilde{y}(t)\| \to 0 \quad \text{for} \quad t \to \infty,$$

which holds true as long as the largest Lyapunov exponent is less than zero. Thus, the value of the largest Lyapunov exponent determines stability, while its fluctuations are essential for the stability-instability transition. We note that there exist a few general theorems claiming Gaussian fluctuations of the largest Lyapunov exponent, see e.g. [45]. However, none of these are directly applicable in the limit of high dimensionality, $N \to \infty$. The heuristic understanding of this breakdown is that the theorems implicitly require a gap between the largest and second largest Lyapunov exponent, while the Lyapunov spectrum often becomes continuous when $N \to \infty$.

For isotropic Brownian motions over real vector fields, explicit formulae for the Lyapunov spectrum were obtained 30 years ago [5, 6, 21]. However, these exponents do not capture the fluctuations in the dynamics at finite times. A more challenging problem is to study the statistical properties of the spectrum of the strain matrix as a function of time, and thereby gain information about the finite-time Lyapunov exponents. Such results can be used to further study the double scaling limit where both the time $t$ and the dimension $N$ tend to infinity. This adds interest since non-trivial scaling regimes are expected.

The remainder of this paper is organised as follows. In section 2 we show how to pass from the matrix-valued Itô equation (5) to the Fokker–Planck equation for the finite-time Lyapunov exponents, including the case of complex fields. In section 3 we show that the Fokker–Planck equation coincides with the one encountered in the phase-coherent transport problem, which is exactly solvable in the complex case, and provide an explicit, compact expression for the joint probability density function. Based on this expression, we also explain the connection to biorthogonal ensembles and Hamiltonian models with an external source. The final section is devoted to the discussion in terms of May–Wigner stability analysis, and a description of further open problems and possible applications. In the appendix we recall the relation between isotropy and the Gaussian elliptic ensemble.

## 2 Fokker–Planck equation for finite-time Lyapunov exponents

Our goal in this section is to find the Fokker–Planck equation for the finite-time Lyapunov exponents. To do this, we need to look at the time evolution of the eigenvalues of the strain matrix $S(t)$. The easiest way to proceed is to use the product formulation (8).

Let us denote the eigenvalues of the strain matrix by $s_1(t), \ldots, s_N(t)$. Since the strain matrix is Hermitian, it follows from ordinary perturbation theory that

$$\delta s_i(t) := s_i(t + \delta t) - s(t) = \delta S_{ii} + \sum_{j \neq i} \frac{\delta S_{ij} \delta S_{ji}}{s_i(t) - s_j(t)} + \text{higher orders}$$

where, according to (8), we have

$$\delta S_{ij} = \sigma \delta t^{1/2} (s_j X_{ji}^* + s_i X_{ij}) + \sigma^2 \delta t \left( 2\mu s_i \delta_{ij} + \sum_k (s_k X_{ki}^* X_{kj} - s_i \mathbb{E}[X_{ik} X_{kj}]) \right) + O(\delta t^{3/2}).$$

4
If we consider evolutions over real vector fields we have $X^* = X$, but we keep the notation general to also account for evolutions over complex fields.

In order to find the Fokker–Planck equation for the eigenvalues of the strain matrix, we use the product formulation (8) and write down a recursive formula for the matrix density of the random evolution matrix $\Pi(n \delta t)$. Upon expansion in $\delta t$ and taking the limit $\delta t \to 0 \ (n \to \infty)$, this recursion produces a differential equation for the matrix density. Finally, the Fokker–Planck equation is obtained by taking the expectation value of the empirical density with respect to the matrix density. This gives

$$
\frac{\partial}{\partial t} \rho_t(s_1, \ldots, s_N) = \lim_{\delta t \to 0} \sum_{i=1}^{N} \frac{\partial}{\partial s_i} \left( -E \left[ \frac{\delta s_i}{\delta t} \right] + \frac{1}{2} \sum_{j=1}^{N} \frac{\partial}{\partial s_j} E \left[ \frac{\delta s_i \delta s_j}{\delta t} \right] \right) \rho_t(s_1, \ldots, s_N),
$$

(13)

where $\rho_t(s_1, \ldots, s_N)$ is the joint probability density function for the eigenvalues at time $t$. The next step is to note that (11) and (12) imply

$$
\lim_{\delta t \to 0} E \left[ \frac{\delta s_i}{\delta t} \right] = s_i \rho_t(s_1, \ldots, s_N),
$$

(14)

and

$$
\lim_{\delta t \to 0} E \left[ \frac{\delta s_i \delta s_j}{\delta t} \right] = 2 s_i s_j (\text{Re}[X^*_i X_{ii}] + \text{Re}[X^*_i X_{jj}]),
$$

(15)

which by insertion in (13), at least in principle, provides an explicit expression for the Fokker–Planck equation for the eigenvalues of our strain matrix.

With the random matrix $X$ distributed according to the density (9), we have covariances

$$
\beta = 1 : \quad E[X_{ij} X_{kJ}] = \delta_{ik} \delta_{j\ell} + \tau \delta_{i\ell} \delta_{jk} \quad \text{(with $X^*_i = X_{ij}$,)}
$$

(16)

$$
\beta = 2 : \quad E[X^*_i X_{kJ}] = \delta_{ik} \delta_{j\ell}, \quad E[X_{ij} X_{kJ}] = E[X^*_i X^*_k] = \tau \delta_{i\ell} \delta_{jk}.
$$

(17)

Introducing these covariances into the above-given formulae, we obtain the Fokker–Planck equation

$$
\frac{\partial}{\partial t} \hat{\rho}_t^\beta(s_1, \ldots, s_N) = \frac{4 \kappa}{\beta} \sum_{i=1}^{N} \frac{\partial}{\partial s_i} \left( \frac{(2 - \beta + N) \beta}{2} s_i - \beta s_i^2 \sum_{j=1 \atop j \neq i}^{N} \frac{1}{s_i - s_j} + s_i^2 \sum_{j=1 \atop j \neq i}^{N} \frac{\partial}{\partial s_i} \right) \hat{\rho}_t^\beta(s_1, \ldots, s_N)
$$

$$
+ 2 \mu \sum_{i=1}^{N} \frac{\partial}{\partial s_i} \hat{\rho}_t^\beta(s_1, \ldots, s_N).
$$

(18)

Here, the first line on the right-hand side represents a diffusive term with diffusion constant given as $\kappa = (1 + \tau) \sigma^2 / 2$, while the second line represents a drift term.

The final step is a change of variables from the eigenvalues of the strain matrix to the exponents $\{\lambda_k := \frac{1}{2} \log s_k\}$. After some standard manipulations, we find the Fokker–Planck equation for the exponents,

$$
\frac{\partial}{\partial t} \hat{\rho}_t^\beta(\lambda_1, \ldots, \lambda_N) = \frac{\kappa}{\beta} \sum_{i=1}^{N} \left( \frac{\partial}{\partial \lambda_i} \frac{\partial}{\partial \lambda_i} + \beta \frac{\partial \Omega(\lambda)}{\partial \lambda_i} \right) \hat{\rho}_t^\beta(\lambda_1, \ldots, \lambda_N) + \mu \sum_{i=1}^{N} \frac{\partial}{\partial \lambda_i} \hat{\rho}_t^\beta(\lambda_1, \ldots, \lambda_N)
$$

(19)

with repulsion term and initial condition given by

$$
\exp[-\Omega(\lambda)] = \prod_{1 \leq i < j \leq N} \sinh(\lambda_j - \lambda_i) \quad \text{and} \quad \lim_{t \to 0} \hat{\rho}_t^\beta(\lambda_1, \ldots, \lambda_N) = \prod_{i=1}^{N} \delta(\lambda_i),
$$

(20)

respectively. Here, the latter condition originates from the fact that the random evolution matrix is required to be equal to unity at $t = 0$. 

5
We could alternatively write (19) as

$$\frac{\partial \rho^\beta_i(\lambda_1, \ldots, \lambda_N)}{\partial t} = \sum_{i=1}^N \left( \frac{\kappa}{\beta} \frac{\partial^2 \rho^\beta_i(\lambda_1, \ldots, \lambda_N)}{\partial \lambda_i^2} + \mu \frac{\partial \rho^\beta_i(\lambda_1, \ldots, \lambda_N)}{\partial \lambda_i} \right) - \kappa \sum_{i,j=1}^N \frac{\partial}{\partial \lambda_i} \left( \rho^\beta_i(\lambda_1, \ldots, \lambda_N) \tanh(\lambda_i - \lambda_j) \right),$$

(21)

which more closely resembles the notation chosen by Dyson [1].

The Fokker–Planck equation (19) is our main result in this section. In the next section, we will show that this equation is exactly solvable for $\beta = 2$. However, before this a few remarks are in order.

We first note that the diffusive term in (19) vanishes as $\tau \to -1$; recall that $\kappa = (1 + \tau)\sigma^2/2$. This absence of diffusion occurs since the random evolution matrix $\Pi_{\mu=0}(t)$ is unitary when $\tau = -1$. It follows that the eigenvalues of the strain matrix $S(t) = \Pi_{\mu=0}(t)\Pi_{\mu=0}(t)$ are all identical and equal to $-\mu t$.

As a second remark, we recall that the Lyapunov exponents $\bar{\mu}_k = \lim_{t \to -\infty} \lambda_i(t)/t$. In the real case ($\beta = 1$) and $\mu = 0$ these limiting values were originally found by Le Jan [5] using methods from Itô calculus (see also [6]). An alternative approach was introduced by Newman [21] shortly thereafter. Newman’s method builds on [46] and uses isotropy to rewrite the determinant of a product of random matrices as a sum, which can then be evaluated using the law of large numbers. These papers focus solely on real evolutions, but the approach is easily extended to include complex matrices (see [38, 40, 42, 23] for a short discussion of such an extension in a slightly different context). In our case, the Lyapunov exponents $\bar{\mu}_k$ are found to be

$$\bar{\mu}_k = \kappa(2k - 1 - N) - \mu, \quad k = 1, \ldots, N.$$

(22)

They are independent of $\beta$ and equidistantly spaced over the interval $(-\kappa N - \mu, \kappa N - \mu)$. Evidently, if we take $\sigma^2 = 1/N$ and thus $\kappa = (1 + \tau)/2N$, we have convergence of the global spectral density to a “square law” on an interval of length $1 + \tau$, centred at $-\mu$. This applies to the iterated limit where $t \to \infty$ followed by $N \to \infty$, for which the square law was originally pointed out by Newman [21]. More recent results for products of random matrices lead us to believe that this law is independent of the order of the limits [47, 40, 23].

The convergence of the global spectrum allows us to establish a stability phase diagram in the large $N$ and $t$ limit. With the aforementioned scaling, the system is stable if $(1 + \tau)/2 < \mu$ and unstable if $(1 + \tau)/2 > \mu$. The Lyapunov exponents themselves can however not be used to describe the finer structure of the phase transition; this requires information about their fluctuations. The Fokker–Planck equation (19) is a good starting point for a study of such fluctuations.

Heuristically, the emergence of the Lyapunov exponents (22) from the Fokker–Planck equation (19) may be understood by realising that for finite $N$, the eigenvalues separate exponentially fast compared with the eigenvalue repulsion. Thus, with the ordering $\lambda_1 \ll \cdots \ll \lambda_N$, in the long-time limit

$$\frac{\partial \Omega(\lambda)}{\partial \lambda_k} \approx 2k - N - 1.$$

(23)

With this approximation the Fokker–Planck equation (19) turns into $N$ uncoupled heat equations. The exponents are seen to be independently Gaussian distributed, and in the long-time limit agree with (22).

The benefit of the Fokker–Planck equation (19) is that it provides information about the statistical properties of the exponents at all times $t$. This is in contrast to Newman’s method and its extensions, which only apply when $\kappa t \gg N$.

3 Solving the Fokker–Planck equation over complex fields

In this section, we show that the Fokker–Planck equation (19) is exactly solvable in the complex case, i.e. for $\beta = 2$. We exploit that a specific version of the Fokker–Planck equation appears for a matrix model
Here, the second term on the right-hand side is seen to be a constant by exploiting an identity for cyclic straightforward. By insertion of the definition of $\Omega(\lambda)$ which turns out to be of Calogero–Sutherland type [48, 49, 50]. The evaluation of the potential is free particles. This is the feature which ensure solvability for $\beta = 2$. Consequently the pair interaction vanishes for $\beta = 2$, and the Hamiltonian in (25) becomes that of $N$ free particles. This is the feature which ensure solvability for $\beta = 2$.

Now, we can return to the Schrödinger equation (25). For the rest of this section we will restrict our attention to the case $\beta = 2$ only, and leave out the index for notational simplicity.
It follows from the parametrisation (24) that the wave function $\psi_t$ must be anti-symmetric in both $\lambda_1, \ldots, \lambda_N$ and $\nu_1, \ldots, \nu_N$, since the joint density $\tilde{\rho}_t$ is symmetric while $\Omega(\lambda)$ is anti-symmetric. Combining this with the absence of pair interactions in (25) allows us to write the wave function as a Slater determinant,

$$\psi_t(\lambda_1, \ldots, \lambda_N | \nu_1, \ldots, \nu_N) = \frac{e^{-Ut}}{N!} \det_{1 \leq i,j \leq N} [g_j^i(\lambda_i)],$$

(30)

where $U = \kappa(N + 1)N(N - 1)/3$ is the constant contribution to the potential energy (29), while each $g_j^i(\lambda)$ satisfies a heat equation

$$\frac{\partial g_j^i(\lambda)}{\partial t} = \frac{\kappa}{2} \frac{\partial^2 g_j^i(\lambda)}{\partial \lambda^2}, \quad g_j^i(\lambda) = \delta(\lambda - \nu_j).$$

(31)

This can be verified by inserting the wave function (30) into the Schrödinger equation (25). The solution to the heat equation (31) is a Gaussian,

$$g_j^i(\lambda) = \frac{1}{\sqrt{2\pi \kappa t}} \exp \left[ - \frac{(\lambda - \nu_j)^2}{2\kappa t} \right].$$

(32)

Now, as a consequence of (24), we know that the joint density is

$$\tilde{\rho}_t(\lambda_1, \ldots, \lambda_N) = e^{-U} \det_{1 \leq i,j \leq N} [g_j^i(\lambda_i)] \prod_{1 \leq i < j \leq N} \sinh(\lambda_j - \lambda_i) \sinh(\nu_j - \nu_i),$$

(33)

assuming a non-singular initial condition $\lambda_1 < \ldots < \lambda_N$. We note that (33) reduces to a product of Dirac delta functions in the $t \to 0$ limit, as required.

We are interested in the singular initial condition $\nu_1 = \ldots = \nu_N = 0$, which may be obtained from (33) by successive use of l'Hôpital's rule. Upon reordering of rows or columns, we find

$$\tilde{\rho}_t(\lambda_1, \ldots, \lambda_N) = e^{-U} \prod_{k=1}^{N} e^{-\frac{\lambda_k^2}{2\kappa t}} \prod_{1 \leq i < j \leq N} \left( \frac{\lambda_j - \lambda_i}{\kappa t} \right) \sinh(\lambda_j - \lambda_i).$$

(34)

To further simplify the expression for the joint density, we first need to make an observation about the Lyapunov exponents from the previous section. At zero drift ($\mu = 0$), we have

$$\sum_{j=1}^{N} \tilde{\mu}_j^2 = \kappa U,$$

(35)

where $\tilde{\mu}_j$ are the Lyapunov exponents and $U$ is the constant contribution to the potential energy as above. Now, combining this with the standard relations

$$\prod_{1 \leq i < j \leq N} (\lambda_j - \lambda_i) = \det_{1 \leq i,j \leq N} [\lambda_i^{j-1}] \quad \text{and} \quad \prod_{1 \leq i < j \leq N} \sinh(\lambda_j - \lambda_i) = \det_{1 \leq i,j \leq N} [\frac{1}{2} e^{2(N-2j+1)\lambda_i}],$$

(36)

we arrive at a surprisingly simple expression for the joint density,

$$\tilde{\rho}_t(\lambda_1, \ldots, \lambda_N) = \left( \prod_{k=1}^{N} \frac{1}{\kappa t} \right) \det_{1 \leq i,j \leq N} \left[ \left( \frac{\lambda_i}{2\kappa t} \right)^{j-1} \right] \det_{1 \leq i,j \leq N} \left[ e^{-(\lambda_i - \tilde{\mu}_j)^2/2\kappa t} \right].$$

(37)

We recall that $\kappa = (1 + \tau)\sigma^2/2$, while the $\tilde{\mu}_j$ are given by (22). The joint density (37) takes the form of a Vandermonde determinant times a determinant of Gaussians with means related to the Lyapunov exponents. The long-time asymptotics mentioned in the previous section thus follow straightforwardly.
Moreover, we note that even though the derivation above was performed with zero drift ($\mu = 0$), the drift can at this point be reintroduced without any change to the joint density (37). The normalisation may be checked using Andreev's integration formula [51, 52].

The joint density (37) describes a special type of biorthogonal ensembles [53] which have been coined polynomial ensembles [54, 55]. This type of ensembles has recently gained renewed attention partly due to their prominent role in the study of the singular values of random matrix products, see e.g. [22]. In the case of product ensembles, the Gaussian weights within the second determinant in (37) are replaced with weights given in terms of Meijer G-functions. In this way, isotropic Brownian motions fit neatly into the picture of recent developments regarding products of random matrices.

There is also a direct relation between our joint density (37) and another well-known matrix ensemble, the Gaussian Unitary Ensemble (GUE) with an external source (see [24, 25, 26] with references and also [56, 57]). This ensemble is based on an $N \times N$ random Hermitian matrix, $H$, distributed with respect to the measure

$$P_A[dH] = \frac{1}{Z} \exp \left[ -\frac{1}{2\kappa^2} \text{Tr} H^2 + \frac{1}{\kappa} \text{Tr} HA \right] dH,$$

where $Z$ is a normalisation constant, $2\kappa t$ is the variance, and $A$ is an $N \times N$ Hermitian external source matrix which without loss of generality may be taken to be diagonal, $A := \text{diag}(a_1, \ldots, a_N)$. The joint density for the eigenvalues of $H$ is obtained by integrating out irrelevant degrees of freedom using the Harish-Chandra–Itzykson–Zuber integral [58, 59]. One then finds

$$\tilde{\rho}_N(\lambda_1, \ldots, \lambda_N) = \frac{1}{Z} \det_{1 \leq i, j \leq N} \left[ \frac{1}{2\kappa} \right] \det_{1 \leq i, j \leq N} \left[ e^{-(\lambda_i - a_j)^2 / 2\kappa t} / \sqrt{2\pi \kappa t} \right]$$

(39)

with $\lambda_1, \ldots, \lambda_N$ denoting the eigenvalues of $H$ and $\tilde{Z}$ representing the corresponding normalisation constant. Here, it is assumed that $a_i \neq a_j$ for $i \neq j$.

The similarity between (39) and (37) is immediately recognised. Thus the Lyapunov exponents in (37) may be interpreted as equidistantly spaced eigenvalues of an external source matrix, as considered e.g. in [60]. While relations between ensembles with an external source and non-intersecting Brownian motions are not new (see [26] and references within), the isotropic Brownian motions studied in this paper provide an example where the external source arises naturally; rather than from an imposed boundary condition.

4 Conclusions and open problems

In this paper we have studied a family of stochastic processes with isotropic matrix-valued multiplicative noise. We have shown that it is possible to formulate a Fokker–Planck equation for the finite-time Lyapunov exponents, and that this Fokker–Planck equation is exactly solvable for evolutions over complex fields, where they give rise to a biorthogonal ensemble. We motivated this stochastic process by its relation to a May–Wigner-like stability analysis for trajectories in an $N$-dimensional space, characterized by a mean relaxation rate $\mu$, a noise strength $\sigma$, and a parameter $\tau \in (-1, 1)$ which characterizes the rotational nature of the flow ($\tau = 1$ represents a pure gradient flow). For a noise variance $\sigma^2 = 1/N$, the infinite-time Lyapunov spectrum has compact support, and converges to a uniform distribution on an interval with length $1 + \tau$ centred at $-\mu$. This allows us to establish a phase diagram for the system in the large-$N$ limit, according to which trajectories are stable if $(1+\tau)/2 < \mu$ and unstable if $(1+\tau)/2 > \mu$.

The heuristic argument at the end of section 2 suggests that the fluctuations of the largest Lyapunov exponent become Gaussian in the limit $kt \gg N$, with more rigorous formulations of this statement following from [5, 46]. It is more challenging to investigate the fluctuations away from this limit, where they are expected to be non-Gaussian. Here, the Fokker–Planck equation established in this paper provides a good starting point. In particular, we note that $kt \ll N$ results in a limit where adjacent stability exponents are close compared to their correlations length. With this in mind, we may substitute $\tanh(\lambda_j - \lambda_i) \approx (\lambda_j - \lambda_i)$ in (21), which transforms the Fokker–Planck equation into an ordinary Dyson
diffusion. This suggests that the largest Lyapunov exponent follows the so-called Tracy–Widom law. Similar approximations may be made starting with the joint density function from section 3. We note that this conjectural transition from a classical random matrix law (Tracy–Widom distribution) to a Gaussian law is not completely unfamiliar; in [61] it was shown that the largest eigenvalue (in terms of absolute value) for a product of complex Ginibre matrices undergoes a transition from a Gumbel distribution to a log-normal distribution.

Future work may be directed towards establishing this transition, and extending it to a detailed description of the stability-instability phase transition, including the critical exponents. From a more mathematical perspective, there are many other intriguing questions worth pursuing beyond the fluctuations of the largest Lyapunov exponent. This includes, but is not limited to, a study of the global spectrum as a function of time, and the local correlations in the bulk as well as near the edge at fixed time $t$.

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A Isotropic measures and elliptic ensembles

In this appendix we briefly recall the construction of isotropic Gaussian matrix measures and their relation to Gaussian elliptic ensembles. We will consider the real ($\beta = 1$) and the complex ($\beta = 2$) case separately.

First, let us look at real matrices; our description closely follows that of [5]. We are considering the family of Gaussian probability measures on the space of $N \times N$ real matrices, where each entry is (centred) Gaussian distributed. Any such measure is uniquely determined by its covariance tensor, $E[X_{ij}X_{k\ell}]$. Imposing isotropy implies that the measure must be invariant under all orthogonal similarity transformations, $X \mapsto UXU^T$. On the level of the covariance tensor, this statement becomes

$$E[X_{ij}X_{k\ell}] = \sum_{i,j,k,\ell=1}^N U_{i'i'}U_{j'j}U_{k'k}U_{\ell'\ell}E[X_{ij}X_{k\ell}]$$

for all $U \in O(N)$. Consequently, any isotropic measure has a covariance tensor given by

$$E[X_{ij}X_{k\ell}] = a\delta_{ij}\delta_{k\ell} + b\delta_{ik}\delta_{j\ell} + c\delta_{i\ell}\delta_{jk}$$

with $a, b, c$ denoting constants unaffected by orthogonal similarity transformations. To understand the interpretation of these constants, we note that

$$E[(X_{ii})^2] = a + b + c \geq 0 \quad \text{and} \quad \frac{1}{2}E[(X_{ij} \pm X_{ji})^2] = b \pm c \geq 0 \quad (i \neq j).$$

Thus, we may write the random matrix $X$ as a sum

$$X = \sqrt{\frac{b+c}{2}} H + \sqrt{\frac{b-c}{2}} A + \sqrt{a} \xi \mathbb{1},$$

where $H$ is a symmetric matrix with standard Gaussian entries (i.e. GOE), $A$ is a skew-symmetric matrix with standard Gaussian entries (i.e. skew-GOE), and $\xi$ is a standard Gaussian random variable. Setting $a = 0$, $b = 1$, and $c = \tau \in (-1, 1)$ result in the elliptic density (9) with $\beta = 1$.

We can now turn to complex matrices ($\beta = 2$). Here, we need to take two covariance tensors into account when determining the most general Gaussian measure, $E[X_{ij}^*X_{k\ell}]$ and $E[X_{ij}X_{k\ell}] (= E[X_{ij}^*X_{k\ell}^*])$. 

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Isotropy says that the measure should be invariant under unitary similarity transformations, \( X \mapsto U^\dagger XU \), which means that

\[
\mathbb{E}[X_{ij'}X_{k'l'}] = \sum_{i,j,k,l=1}^{N} U^*_{i'j'}U^*_{k'l'}U_{j'k}U_{i'l}\mathbb{E}[X_{ij}X_{k'l}],
\]

\[
\mathbb{E}[X_{ij'}^*X_{k'l'}] = \sum_{i,j,k,l=1}^{N} U_{i'j'}U_{k'l'}U^*_{j'k}U^*_{i'l}\mathbb{E}[X_{ij}X_{k'l'}],
\]

for all \( U \in \mathbb{U}(N) \). Thus

\[
\mathbb{E}[X_{ij}X_{k'l'}] = a \delta_{ij}\delta_{k'l'} + b \delta_{i'l}\delta_{jk'}
\]

and

\[
\mathbb{E}[X_{ij}^*X_{k'l'}] = c \delta_{ij}\delta_{k'l'} + d \delta_{i'l}\delta_{jk'},
\]

where \( a, b, c, d \) are constants. Similar to the real case, we will look at correlations to obtain an interpretation of these constants. We then find

\[
\frac{1}{2}\mathbb{E}[|X_{ii} \pm X_{ii}^*|^2] = c + d \pm (a + b) \geq 0 \quad \text{and} \quad \frac{1}{2}\mathbb{E}[|X_{ij} \pm X_{ji}^*|^2] = d \pm b \geq 0 \quad (i \neq j),
\]

and can therefore write the random matrix \( X \) as a sum

\[
X = \sqrt{\frac{d + b}{2}} H + \sqrt{\frac{d - b}{2}} A + (\sqrt{c} \xi + i\sqrt{d} \eta) \mathbb{1},
\]

where \( H \) is a Hermitian matrix with standard complex (real on the diagonal) Gaussian entries (i.e. GUE), \( A \) is a skew-Hermitian matrix with standard complex (imaginary on the diagonal) Gaussian entries (i.e. skew-GUE), while \( \xi \) and \( \eta \) are standard real Gaussian random variables. Analogously to before we set \( a = 0, b = \tau \in (-1, 1), c = 0, \) and \( d = 1 \), which results in a random matrix with density (9).

References


